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# Adding a point to vector diagrams in multivariate analysis 

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## Rothamsted Experimental Station

## Summary

A set of $n$ base points $P_{i}(i=1,2, \ldots, n)$, with known co-ordinates relative to orthogonal axes, and a further point $P_{n+1}$, with known distance from each of the base set, are given. The co-ordinates of $P_{n+1}$ relative to the axes of the base set are found. The formula is particularly simple when the base set is referred to its principal axes, when the co-ordinates of $P_{n+1}$ for a subset of all the axes can be calculated from the co-ordinates of the $P_{i}$ in this subset only. The classical results for edding a point to a principal components or canonical variatee analyses are obtained when the base set is derived using the appropriate distance functions. An example is given.

## 1. Derivation of the basio formula

Gower ( $1966 a$ ) discussed how the co-ordinates of $n$ points $P_{i}(i=1,2, \ldots, n)$ referred to principal axes can be found, given the Euclidean distances $d_{i j}$ between all point pairs $P_{i}$ and $P_{j}$; principal components and canonical variate analysis are special cases. The points are supposed to lie in an $m$-dimensional space; normally $n=n-1$ but in exceptional cases $m$ can be leas. The successive steps in this method may be summarized as follows:
(i) define the matrix A whose elements are $-\frac{1}{8} d_{i j}^{2}$;
(ii) define $\mathbf{B}$ with elements $b_{i j}=a_{i j}-a_{i .}-a_{. j}+a_{\text {. }}$;
(iii) find the $m$ non-zero latent roots $\dot{\Lambda}=\operatorname{diag}\left(\ddot{\lambda}_{1}, \lambda_{2}, \ldots, \lambda_{m}\right)$ of $\mathbf{B}$ and corresponding vectors $\mathbf{X}$ standardized so that $\mathbf{X}^{\prime} \mathbf{X}=\boldsymbol{\Lambda}$. Thus $\mathbf{B X}=\mathbf{X} \boldsymbol{\Lambda}$ and

$$
\begin{equation*}
\mathbf{X X}^{\prime}=\mathbf{B} \tag{1}
\end{equation*}
$$

The $i$ th row of $\mathbf{X}$ gives the co-ordinates ( $x_{i 1}, x_{i 2}, \ldots, x_{i m}$ ) of $P_{i}$; the points are centred so that the origin is at the centroid $G$, i.e. the column sums of $X$ are zero. When $B$ is not positive semi-definite some velues of $\lambda_{i}$ will be negative and all co-ordinate values along the corresponding axes will have imaginary values. In this case the distances cannot be Euclidean but the resulta given here remain valid if we accept imaginary values in the usual distance formula $d_{i 1}^{1}=\left(x_{i 1}-x_{i 1}\right)^{\mathbf{3}}+\ldots+\left(x_{i m}-x_{j m}\right)^{\mathbf{2}}$.

The ith diagonal element of $\mathbf{X} \mathbf{X}^{\prime}$ may be written $x_{i 1}^{*}+\ldots+x_{i m}^{i}$; this is the square of the distance $d_{i}$ of $P_{i}$ from the centroid, and therefore from (1)

$$
\begin{equation*}
b_{i t}=d_{i}^{t} \tag{2}
\end{equation*}
$$

a result which will be needed later. The geometrical interpretation of the off-diagonal elemente of $\mathbf{B}$ is that $b_{i j}=d_{i} d_{j} \cos \theta_{i j}$, where $\theta_{i j}$ is the angle subtended by the line $P_{i} P_{j}$ at the centroid, but this result will not be needed here.

When a further point becomes available, a method is needed for finding its co-ordinates

$$
P_{n+1}\left(x_{n+1,1}, x_{n+1,2}, \ldots, x_{n+1, m}, x_{n+1, m+1}\right)
$$

relative to the axes used for the $P_{i}(i \leqslant n)$, allowing for an $(m+1)$ th dimension which may be needed to represent exactly all the new given distances $d_{i, n+1}(i=1,2, \ldots, n)$. The co-ordinates can be found by solving the $n$ quadratic equations

$$
\begin{equation*}
d_{i, x+1}^{n}=\sum_{k=1}^{m+1}\left(x_{n+1}, k-x_{i, k}\right)^{2} \quad(i=1,2, \ldots, n) \tag{3}
\end{equation*}
$$

where $x_{i, m+1}=0$ when $i \neq n+1$.
Before showing how the equations (3) can be conveniently solved, a few remarks are appropriate. In principal component analyses the point $P_{n+1}$ will not need an extra dimension for ite representation, unless $m$ happens to be less then the total number of variates in the analysis, and the distances $d_{i, n+1}$ can be readily computed from the data. Because $x_{n+1, k}$ is the orthogonal projection of $P_{n+1}$ onto the $k$ th exis, the solution of (3) using these distances must agree with the clessical method for adding a point in a principal components analysis; similar remarks apply to canonical variate analysis. This result, obvious geometrically, is verified below algebraically. Although $m$ will always be less than $n$ so that some of the $n$ equations in (3) must be redundant, it is evident from the geometrical derivation that these
equations are consistent. For example, if $n=10$ and $m=1$ so that the base set consists of 10 collinear points, $P_{11}$ is fixed by two distances, say $d_{1,11}$ and $d_{k, 11}$, but the remaining 8 distances will be consistent with these two. Even in the worst case there are enough equations to find all $m+1$ co-ordinates of $P_{n+1}$, for then the $n$ base points will require $n-1$ dimensions for their representation so that $m+1 \leqslant n$.

To solve (3), the equations will first be written in the alternative form

$$
\begin{equation*}
d_{i, n+1}^{\mathrm{L}}=d_{n+1}^{2}+d_{i}^{1}-2 \sum_{k=1}^{m} x_{i k} x_{n+1, k} \quad(i=1,2, \ldots, n) . \tag{4}
\end{equation*}
$$

Because of the centring, the cross-product term in (4) vanishes when these equations are summed over $i$. Thus

$$
\begin{equation*}
\sum_{i=1}^{n} d_{i, n+1}^{2}=n d_{n+1}^{2}+\sum_{i=1}^{n} d_{i}^{2}, \tag{5}
\end{equation*}
$$

which can be used to substitute for $d_{n+1}^{2}$ in (4), giving after a little rearrangement

$$
\begin{equation*}
2 \sum_{k=1}^{m} x_{i k} x_{n+1, k}=d_{i}^{2}-d_{i, n+1}^{2}-\frac{1}{n} \sum_{i=1}^{n}\left(d_{i}^{2}-d_{i, n+1}^{2}\right) \tag{6}
\end{equation*}
$$

This is $\mathbf{a}$ set of $n$ linear equations in the $m$ unknowns $x_{n+1, k}(k=1,2, \ldots, m)$. These equations are consistent because they have been derived by linear operations from the set of consistent equations (3). As all the distances on the right-hand side of (6) are known, the first $m$ equations may be solved to find the required values, but a more symmetric method is convenient. First putting ( 8 ) into matrix form by defining $x^{\prime}$ to be the $\mathbf{l} \times m$ vector ( $x_{n+1,1}, x_{n+1,2}, \ldots, x_{n+1, m}$ ), $\mathbf{d}$ to be the $n \times 1$ vector whose ith element is $d_{i}^{2}-d_{i, n+1}^{2}$ and U to be the $n \times n$ matrix all of whose elements are units, we have thet

$$
\begin{equation*}
2 \mathbf{X x}=\mathbf{d}-\frac{1}{n} \mathbf{U d} . \tag{7}
\end{equation*}
$$

Hence on pre-multiplying both sides of (7) by $\mathbf{X}^{\prime}$, and noting thet $\mathrm{X}^{\prime} \mathrm{U}=0$ because of the centring, and inverting, it follows that

$$
\begin{equation*}
\mathbf{x}=\frac{1}{\mathbf{d}}\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1} \mathbf{X}^{\prime} \mathbf{d} . \tag{8}
\end{equation*}
$$

This is a symmetric form of the solution to (7) and gives the co-ordinates of $P_{n+1}$ in the first $m$ dimensions, the value of $x_{n+1, m+1}$ is conveniently obtained by calculating $d_{n+1}$ from (5) and using

$$
\begin{equation*}
x_{n+1, m+1}^{2}=d_{n+1}^{2}-\sum_{k=1}^{m} x_{n+1, k}^{2} \tag{9}
\end{equation*}
$$

Thus the first $m$ co-ordinates are uniquely defined but the ( $m+1$ )th is determined in value but not sign.
So far the principal axis property of $\mathbf{x}$ has not been used; the results (8) and (9) are applicable to any centred base set $\mathbf{X}$ referred to orthogonal axes. When $\mathbf{X}$ is referred to principal axes (8) becomes

$$
\begin{equation*}
\mathbf{x}=\frac{1}{\boldsymbol{q}} \boldsymbol{\Lambda}^{-1} \mathbf{X}^{\prime} \mathbf{d} \tag{10}
\end{equation*}
$$

Because $\Lambda$ is diagonal, the value of $x_{n+1, k}$ is determined solely from $\lambda_{k}$, the $k$ th column of $\mathbf{X}$ and the elements of $\mathbf{d}$. The quantities $d_{i}^{2}$ occurring in $\mathbf{d}$ are diagonal elements of $\mathbf{X X} \mathbf{X}^{\prime}$ and their evaluation would seem to need all the columns of $\mathbf{X}$ but it was shown in (1) that $\mathbf{X X}=\mathbf{B}$, a, matrix whose elements are simply computed and which is in any case needed to compute even only one column of $\mathbf{X}$. Thus if the analysis leading to ( 1 ) is used to give a representation of the base-set of points $P_{i}$ in $r(<m$ ) dimensions, e.g. by ignoring axes with small $\lambda_{k}$, (10) can still be used to find the co-ordinstes of the projections of $P_{n+1}$ on to the reduced space using only $r$ columns of $\mathbf{X}$, the known true distances $d_{i}$ of $P_{i}(i=1,2, \ldots, n)$ from their centroid, obtained from the matrix $\mathbf{B}$, and the known true distances $d_{i, n+1}$. The residuel distance $d_{n+1, r}$ of $P_{n+1}$ from the $r$-dimensional plane is then given by a modification of equation (9) and is

$$
\begin{equation*}
d_{n+1, r}^{2}=d_{n+1}^{z}-\sum_{k=1}^{r} x_{n+1, k}^{2} \tag{11}
\end{equation*}
$$

When the co-ordinates of the base-set are not referred to principal axes formula (8) must be used, and this requires all $m$ columns of $\mathbf{X}$ to compute ( $\mathbf{X} \mathbf{X})^{-1}$.

## 2. Princtipal oomponent and oanonical variate analysis

A simple geometrical argument has shown that (10) must reduce to the desired resulte when edding a point in a principal components or canonical variates analysis. This is not obvious from an inspection of ( 10 ) but is readily verified algebraically.

In a canonical variates analysis on $n$ populations with $v$ measured variates and common dispersion matrix $\mathbf{W}$, the means for the $i$ th population will be written as the $l \times v$ vector $g_{i}(i=1,2, \ldots, n)$. The $n \times v$ matrix $G$ of all the population means has rows $g_{i}$ and is supposed centred so that the column sums, ignoring any differences in population sizes, are zero. The latent roots $\Lambda$ and vectors $L$ satisfying

$$
\begin{equation*}
\mathbf{G}^{\prime} \mathbf{G L}=\mathbf{W L} \mathbf{\Lambda} \tag{12}
\end{equation*}
$$

can be found and the population means referred to canonical variate axes are defined by

$$
\begin{equation*}
\mathbf{X}=\mathbf{G L}, \tag{13}
\end{equation*}
$$

where the vectors are normalized so that $\mathbf{L} \mathbf{W} \mathbf{W}=\mathbf{I}$. Reasons for sometimes using $\mathbf{G}^{\prime} \mathbf{G}$ rather than the usual weighted between-population dispersion matrix were discussed by Gower ( 1966 b ). The co-ordinates $\mathbf{X}$ of the base set are defined by (13) and the usual formula giving the co-ordinates $\mathbf{X}(v \times 1)$ referred to the canonical axes of a new eample $g(1 \times v)$ referred to the original variate axes is

$$
\begin{equation*}
\mathbf{x}=\mathrm{L}^{\prime} \mathbf{g}^{\prime} \tag{14}
\end{equation*}
$$

Mahalanobis's $D^{\mathbf{2}}$ is the appropriate distance for this type of analysis and therefore

$$
\begin{equation*}
d_{n+1, i}^{2}=\left(g-g_{i}\right) \mathbf{W}^{-1}\left(g-g_{i}\right)^{\prime} \quad \text { and } \quad d_{i}^{1}=g_{i} \mathbf{W}^{-1} g_{i}^{\prime} \tag{15}
\end{equation*}
$$

Therefore

$$
\begin{equation*}
d_{i}^{2}-d_{n+1, i}^{2}=2 g_{i} \mathbf{W}^{-1} \mathbf{g}^{\prime}-g W^{-1} g^{\prime} \quad \text { and } \quad \mathbf{d}=2 G W^{-1} g^{\prime}-g W^{-1} g^{\prime} \mathbf{1} \tag{16}
\end{equation*}
$$

where $1^{\prime}$ is an $n \times 1$ vector of units. Insertion of these results in (10) gives

$$
\begin{equation*}
\frac{1}{2} \Lambda^{-1} \mathbf{X}^{\prime} d=\frac{1}{2} \Lambda^{-1} L^{\prime} \mathbf{G}^{\prime}\left(2 G W^{-1} g^{\prime}-g W^{-1} g^{\prime} 1\right) \tag{17}
\end{equation*}
$$

The second term on the right-hand side of (17) vanishes because G'1 $=0$ so that

$$
\frac{1}{8} \Lambda^{-1} \mathbf{x}^{\prime} \mathbf{d}=\Lambda^{-1} L^{\prime} \mathbf{G}^{\prime} \mathbf{G W}^{-1} \mathbf{g}^{\prime}
$$

which simplifies by using the transpose of (12) to

$$
\begin{equation*}
\frac{1}{2} \Lambda^{-1} \mathbf{X}^{\prime} \mathbf{d}=\Lambda^{-1} \Lambda \mathbf{L}^{\prime} W \mathbf{W}^{-1} \mathbf{g}^{\prime}=\mathbf{L}^{\prime} \mathbf{g}^{\prime} \tag{18}
\end{equation*}
$$

agreeing with (14) as required.
The verification for principal components is almost identical, but with $\mathbf{W}$ replaced by $I$, and $G$ interpreted as a $n \times v$ data matrix derived from observations on $v$ variates for a multivariate sample of size $n$.

## 3. Example

Columns 2, 3 and 4 of Table 1 were derived from a table giving the distances $d_{i j}$ between every pair of eleven British cities, using the method described by Gower (1986a) and outlined here in the discussion leading to (1) and (2). These constitute the calculations needed to find the co-ordinates of the bese-set, here in two dimensions, and remain fixed when positioning a new city. The third, fourth and fifth roots are 6878, 2338 and 288, all small compared with the first two, given in Table 1, and the five remaining roots are negative with a total value of - 6966, less in modulus than $\lambda_{3}$. Therefore, although an exact reproduction of the given distances is impossible in two dimensions, or in any number of real dimensions, these co-ordinates give quite a good Euclidean representation of the relative positions of the cities; the road distances as reproduced are, on the average, about 1.13 times the direct distances.

The squared distances $d_{n+1,1}^{2}$ of a further city, Birmingham, from each city of the base set are given in column 5 and the elements of the vector $d$, found by subtracting column 5 from 4, are given in column 6. The latent roots $\lambda_{1}$ and $\lambda_{2}$ found in the base set analysis are required and it can be checked from Table 1 that

$$
\lambda_{1}=\sum_{i=1}^{11} x_{i 1}^{2} \quad \text { and } \quad \lambda_{i}=\sum_{i=1}^{11} x_{i 2}^{2} .
$$

The first co-ordinate $x_{12,1}$ of Birmingham is found as the sum of products of columns (2) and (6) divided by $2 \lambda_{1}$; this gives

$$
\begin{aligned}
& x_{12,1}=-69,6384 \cdot 26 /(2 \times 177,738)=-2 \cdot 0 . \\
& x_{12,2}=-2,241,086 /(2 \times 29,178)=-38 \cdot 4 .
\end{aligned}
$$

Similarly,
The position ( $-2 \cdot 0,-\mathbf{3 8} \cdot 4$ ) places Birmingham very well. Its distance $d_{12}$ from the centroid of the base set is found from equation (5) es

$$
11 d_{19}^{2}=232,505-210,653 \cdot 7=21,851 \cdot 3
$$

Table 1. Quantities needed to determine the position of Birmingham

| 1 | 2 | 3 | 4 | 5 | 6 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| City, ${ }^{\text {i }}$ | $\begin{gathered} x_{i 1} \\ \text { (miles) } \end{gathered}$ | $\begin{gathered} x_{i 2} \\ \text { (miles) } \end{gathered}$ | $d_{i}=b_{i i}$ | $\begin{gathered} d_{x+1, i}^{L} \\ \text { (Birmingham) } \end{gathered}$ | $(4)-(5)=d$ |
| Brighton | $-140.7$ | $9 \cdot 3$ | 21,268.7 | 25,600 | $-4,331 \cdot 3$ |
| Bristol | -72.9 | -92.6 | 14,424.3 | 7,744 | 6,680-3 |
| Cambridge | -39.8 | $52 \cdot 6$ | 3,856.2 | 10,000 | -6,143.8 |
| Edinburgh | $283 \cdot 6$ | $-14 \cdot 9$ | 80,785.9 | 82,944 | -2,158.1 |
| London | $-88.8$ | $20 \cdot 3$ | 8,492-4 | 12,100 | $-3,607 \cdot 6$ |
| Manchester | $78 \cdot 3$ | $-31.9$ | 8,333.3 | 6,400 | 1,933.3 |
| Newcastle | $184 \cdot 3$ | $12 \cdot 1$ | 34,902.0 | 40,401 | - $6,499 \cdot 0$ |
| Norwich | $-43 \cdot 9$ | $113 \cdot 4$ | 15,632.3 | 24,336 | $-8,703 \cdot 7$ |
| Nottingham | $28 \cdot 7$ | $5 \cdot 5$ | 439.7 | 2,500 | -2,060.3 |
| Oxford | $-62.7$ | $-24.1$ | 4,483.8 | 4,096 | $387 \cdot 8$ |
| Southampton | -120.1 | $-49 \cdot 7$ | 18,035.1 | 16,384 | 1,651•1 |
| Latent roots | 177,738 | 29,178 | - | - | - |
| Totals | - | - | 210,653.7 | 232,505 | - |

Columns 1, 2, 3 and 4 are given by the calculations for the base-set and are determined in a preliminary analysis. Column 5 is given and 6 is the difference between 4 and 5 .

Thus $d_{18}^{1}=1986.5$, i.e. minus the mean of column 6 and the residual distance $d_{12, r}$ of Birmingham from the plane of the base set is found from equation (11) to be 22.5 miles. It must be remembered that this residual has real and imaginary components so that $d_{18, r}^{2}$ may become small because of the possible cancellation of large positive and negative componente; this would not be so if the original distances had been Euclidean giving no negative latent roots. In this example the root-mean-square residual of the base set in the direction of the third dimension is $(6878 / 11)^{t}=25 \cdot 0$ miles and the total root-mean-square residual out of the fitted plane, using positive and negative roots, is $(3538 / 11)^{\frac{1}{2}}=17 \cdot 9$ miles, both agreeing well with $d_{12, r}$. However, a critical examination of this residual would require the real and imaginary components, separately.

A glance at an atlas reveals that Birmingham is well within the region covered by the base set and the usual warnings apply to extrapolation outside this region; the position of John O'Groats would be poorly determined with the base set chosen here.

## Referenoes

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