1 2	Title: №	lodel Ensembles of Ecosystem Services Fill Global Certainty and Capacity Gaps		
3	Authors: Simon Willcock ^{1,2±*} , Danny A. P. Hooftman ^{3,4±} , Rachel A. Neugarten ^{5,6,7} , Rebecca Chaplin-			
4	Kramer ^{8,9,10} , José I. Barredo ¹¹ , Thomas Hickler ^{12,13} , Georg Kindermann ¹⁴ , Amy R. Lewis ² , Mats			
5	Lindesk	og ¹⁵ , Javier Martínez-López ^{16,17} & James M. Bullock ⁴		
6	1.	Net Zero and Resilient Farming, Rothamsted Research, Harpenden, Hertfordshire AL5 2JQ,		
7		United Kingdom; simon.willcock@rothamsted.ac.uk		
8	2.	School of Natural Sciences, Bangor University, Bangor, Gwenydd, LL57 2DG, United Kingdom;		
9		amy.lewis@bangor.ac.uk		
10	3.	Lactuca: Environmental Data Analyses and Modelling, the Netherlands;		
11		danny.hooftman@lactuca.nl		
12	4.	UK Centre for Ecology & Hydrology, Wallingford OX10 8BB, United Kingdom; jmbul@ceh.ac.uk		
13	5.	Department of Natural Resources & Environment, Cornell University, 226 Mann Drive, Ithaca		
14		NY 14853 USA; <u>ran63@cornell.edu</u>		
15	6.	Conservation International, 2100 Crystal Drive #600, Arlington, VA 22202, USA		
16	7.	Cornell Lab of Ornithology, Cornell University, 159 Sapsucker Woods Rd, Ithaca, NY 14850, USA		
17	8.	Global Science, Word Wildlife Fund, 131 Steuart Street, San Francisco, CA 94105, USA		
18		becky.chaplin-kramer@wwf.org		
19	9.	Institute on the Environment, University of Minnesota, 1954 Buford Ave, St. Paul, MN, USA		
20	10.	Natural Capital Project, Stanford University, 327 Campus Drive, Stanford CA, USA		
21	11. European Commission, Joint Research Centre, Ispra, Italy; jose.barredo@ec.europa.eu			
22	12.	Senckenberg Biodiversity and Climate Research Centre, Frankfurt, Germany;		
23		thomas.hickler@senckenberg.de		
24	13.	Institute of Physical Geography, Goethe-University, Altenhöferallee 1, 60438 Frankfurt am		
25		Main, Germany.		
26	14.	International Institute for Applied Systems Analysis, Laxenburg, Austria; <u>kinder@iiasa.ac.at</u>		
27	15.	Department of Physical Geography and Ecosystem Science, Lund University, Lund, Sweden;		
28		mats.lindeskog@nateko.lu.se		
29	16.	Department of Ecology, University of Granada, Avda. del Mediterráneo s/n, E-18006 Granada,		
30		Spain; javier.martinez@ugr.es		
31	17.	Instituto Interuniversitario de Investigación del Sistema Tierra en Andalucía (IISTA),		
32		Universidad de Granada, Avda. del Mediterráneo s/n, E-18006 Granada, Spain		
33	[±] Joint 1	L st author		
34	* Corre	sponding author		
35				
36	Teaser			
37	Global	ensembles of ecosystem service models have increased accuracy and fill data gaps for less		
38	wealthy	/ regions		
39				
40	Abstrac	ct (max 150 words)		
41				
42	Sustain	ing ecosystem services (ES) critical to human wellbeing is hindered by many practitioners		
43	lacking	access to ES models ('the capacity gap') or knowledge of the accuracy of available models ('the		
44	certaint	ty gap'), especially in the world's poorer regions. We developed ensembles of multiple models		
45	at an unprecedented global scale for five ES of high policy relevance. Ensembles were 2-14% more			
46	accurate than individual models. Ensemble accuracy was not correlated with proxies for research			
47	capacity – indicating accuracy is distributed equitably across the globe and that countries less able to			
48	research ES suffer no accuracy penalty. By making these ES ensembles and associated accuracy			
49	estimates freely available, we provide globally consistent ES information that can support policy and			
50	decisio	n making in regions with low data availability or low capacity for implementing complex ES		
51	models	. Thus, we hope to reduce the capacity and certainty gaps impeding local to global-scale		

52 movement towards ES sustainability.

- 53
- 54 **Keywords:** Accuracy; Ensemble; Implementation gap; Modelling; Nature's contributions to people; 55 Uncertainty.
- 56

57 Introduction

58

59 There is a burgeoning number of ecosystem service (ES) maps delineating an ever-growing 60 understanding of the ways in which nature benefits people (e.g. 1, 2). However, when ES data are 61 available, they are typically inconsistent between countries, making standardized measurement or 62 reporting difficult (3). Global maps (based on satellite and other data integrated in a variety of models) 63 can provide readily-available information when more locally relevant data are lacking (4). Though, it is 64 questioned whether global maps provide accurate or useful information given their lack of sensitivity 65 to local context (5). It is difficult to answer this question for most large-scale ES modelling exercises 66 due to the lack of information on model accuracy - the closeness of the agreement between the 67 modelled value and a reference value (6), the latter being considered 'true' (7) even though the 68 validation data are also often uncertain (8). Individual model performance varies, validation with 69 empirical data is sometimes lacking, and results are typically reported without estimates of accuracy 70 (8). Two key advantages of global maps are that they can fill gaps in data-poor contexts until local data 71 can be collected or created, and they are consistent among countries (4). For example, at a local level, 72 the Critical Ecosystem Partnership Fund made conservation investment decisions in Madagascar 73 based, in part, on local information on the relative importance of sites for ES derived from models and 74 globally available data (9). At a global scale, consistent data can be used for international policy and 75 decision making [e.g. informing targets and investments in the united Nations (UN) Sustainable 76 Development Goals, the Convention on Biological Diversity post-2020 Biodiversity Framework, the 77 UN's System of Environmental-Economic Accounting-Ecosystem Accounting (10)]. Global data can also 78 provide consistent and comparable local reporting for these international agreements, as well as 79 broader context for local decisions by revealing wider regional, continental and global patterns in ES 80 status and trends (4).

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82 Several studies have validated models of single ES (e.g. 11, 12), and rarely multiple ES (e.g. 8, 13). 83 Independent evaluations of models have often been unable to demonstrate the consistently superior 84 accuracy of any individual model (8, 13). While a few studies find that, on average, more complex ES 85 models show better fit to validation data, the best-fit model varies regionally and often according to 86 the validation data used (8, 13). Thus, decisions based on a single model for an ES are less likely to be 87 robust and, when models are in disagreement, it is difficult for practitioners (those engaging with 88 information from ES models) to know which model should be used to support decisions (14). In fact, 89 projections by alternative models can be so variable as to compromise even the simplest assessment 90 and therefore challenge the common practice of relying on a single method (15). This 'certainty gap' 91 greatly reduces the confidence that practitioners have in projections from ES models (16).

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93 The certainty gap is unlikely to be uniformly distributed across the globe. In developing countries, 94 reliable information about ES is critically important because the rural and urban poor are often the 95 most dependent on ES (directly or indirectly), both for their livelihoods and as a coping strategy for 96 buffering shocks (17). ES declines driven by over-exploitation, habitat conversion or climate change 97 therefore undermine 80% (35 of 44) of the Sustainable Development Goals (SDGs) (18). However, ES 98 data and accuracy estimates are often unavailable in developing nations, or in less affluent regions 99 within nations, where they are most needed (17). There is an urgent need for evaluations of model 100 accuracy to better inform decision making - a need that has been emphasised by the 101 Intergovernmental Science-Policy Platform on Biodiversity and Ecosystem Services (IPBES) (19). To 102 address this, researchers have established standards for best practice using model-data (8) and model-103 model (13, 20) comparisons to provide robust and transparent evaluations of accuracy. For example, 104 an ensemble of models is more accurate, on average, than one model for any location, although the amount of improvement depends on the local context and the models used (*13*, *15*, *20*). However, whilst model ensembles are common in climate modelling and other disciplines (*15*, *21*), they have been largely neglected in ES studies (*22*). Indeed, simple ('committee average') ensembles have been found to be at least 5% more accurate than individual ES models (*13*), while more complex, weighted ensembles provide even better predictions (up to 27% more accurate) (*20*). Furthermore, variation among models can provide an indicator of the uncertainty of the modelled ES estimate when no other information is available (*13*).

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113 Whilst using ensembles of ES models is possible, there are barriers that need to be overcome before 114 it can become standard practice within ES science. Implementing multiple ES models remains a difficult 115 undertaking for many researchers and practitioners (13). Barriers include lack of input data, resources, 116 and capacity for data collection or collation and for modelling (13, 14). As with the certainty gap, these 117 barriers are typically more substantial in poorer nations. For example, to create ensembles of carbon 118 storage models across three major platforms - ARIES (23), InVEST (24) and Co\$ting Nature (25) -119 requires access to the internet, high quality input data, computational power and GIS proficiency, as 120 well as funds to support model subscription fees (where required) and the person-time required to 121 learn and run three different models (13). Such resources can be out of reach for many researchers 122 and practitioners. Furthermore, if practitioners must choose between running multiple models for a 123 single service versus modelling additional services, the former may be of low priority; thus the 124 widespread use of ES ensembles may be an unrealistic goal (13, 14, 20). We refer to the lack of these 125 resources as the 'capacity gap'. One potential solution to the capacity gap is that those who have the 126 resources to create ES ensembles make the resulting data, as well as estimates of uncertainty, freely 127 available (e.g. 13, 20).

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129 To address the certainty and capacity gaps, we developed ensembles of models for five ES (Figure 1) 130 of high global and local policy relevance (14), and for which there are both: i) a variety of models 131 available that are feasible to run at a global scale; and ii) accessible, independent validation data to 132 assess ensemble accuracy. We included three material services (water supply: eight available models; 133 fuelwood production: nine models; and forage production: 12 models); one regulating service (above 134 ground [AG] carbon storage: 14 models); and one non-material service (recreation: five models). Some 135 of these ES are potential services (e.g. water, fuelwood, forage) and some are realised (e.g. carbon 136 recreation); where potential ES are 'the outcomes from ecosystems that directly lead to good(s) that 137 can be used and valued by people (e.g. harvestable products, water supply), noting that some 138 ecosystem services can be both ecosystem processes and potential ecosystem services', and realised 139 ES are 'all use and non-use, material and non-material outputs from ecosystems that are used and 140 valued by people' (26, 27). Both potential and realised service metrics are useful to support decision 141 making; with the latter providing insight into how the wellbeing of people is improved by nature, and 142 the former indicating the maximum capacity of these potential wellbeing increases (14). We used 143 model output predictions and created ES ensembles at an unprecedented global extent and at a 144 0.008333° resolution (approximately 1 km at the equator). We address the capacity gap by making the 145 ensemble model outputs freely available (https://doi.org/10.5285/bd940dad-9bf4-40d9-891b-146 161f3dfe8e86), as well as providing the code (github.com/GlobalEnsembles) to make the overall 147 approach more accessible. To address the certainty gap, we tested the accuracy of these ensembles 148 against independent validation data (including country-level statistics and actual biophysical 149 measurement), and investigated spatial patterns in ensemble accuracy.



 ⁽i.e. multiple ES per modelling framework) and 17 individual ES models (Table 2; B). These models are combined into model ensembles following Hooftman et al. (20), with the number of models in the ensemble for each ES shown in C. We use validation data on each ES to test accuracy of the ensembles to both their own service and as proxy for other services (D). Symbol key: †Including choice of input data; ‡
 Including models created by masking of above ground (AG) carbon models with woody (fuelwood) or grassland land use masks [see (8); SI 3]; § combined pan-tropical biomass reference data (28) and United Kingdom (temporal) AG biomass stocks in forest estates (20). See Methods for full details.





161 162 163 164 165 166 167 168 certainty gap, we show the standard error of the mean associated with each ES ensemble output which, in accordance with previous research (13), our investigations show can be used a proxy for ensemble accuracy in absence of validation data (Figure S4). All maps scaled 169 170 in deciles 0-100%. True zero values (coloured) are distinguished from no-data (white). Selected case study regions are shown in SI-6. The figures are available via https://github.com/GlobalEnsembles/Maps, and the data are available via https://doi.org/10.5285/bd940dad-9bf4-171 40d9-891b-161f3dfe8e86.

172 Here, we present results using an unweighted median ensemble (8) approach (i.e. taking the median 173 value of multiple models for each grid cell; Figure 2). Other ensemble approaches, including 174 unweighted (mean), and weighted (deterministic consensus: PCA & correlation coefficient; iterated consensus: regression to the median and leave-one-out cross validation log-likelihood) approaches) 175 176 (20), which give consistent conclusions, are described in the SI. When compared to independent 177 validation data (Figure 1, Table 3), global ES ensembles were more accurate than an individual model 178 chosen at random (Table 1, Figure 3). Median ensemble improvement per validation data point for 179 each ES was 14% for water (resolution of the validation data: weir defined watersheds), 6% for 180 recreation (national-scale), 6% for above ground (AG) carbon (plot-scale), 3% for fuelwood (nationalscale), and 3% for forage production (national-scale; Table 1, Figure 3). Thus, using global ES ensembles 181 182 rather than an individual ES model reduces the certainty gap for practitioners with no a priori 183 information on model accuracy. In general, the weighted ensembles provided more accurate 184 predictions than unweighted ensembles (Figure S15 and S16), and so should be favoured by 185 practitioners. Ensembles further address the certainty gap by transparently conveying any spatial 186 variation in accuracy. For example, the standard error of the mean associated with each ES ensemble 187 (Figure 2) correlates with the accuracy of the ensemble and so can be used as a proxy for ensemble 188 accuracy in absence of validation data [(13) and Figure S4], indicating the accuracy of the ensembles in any specific geographic location. Our results are consistent when using alternative accuracy metrics 189 190 (e.g. Spearman's ρ ; see SI-5).





202 203 Whilst the results presented here show ES ensembles reduce the certainty gap, differences in 204 ensemble performance between regions or countries might be expected. For example, nations 205 investing more in research capacity might have better input data or have more researchers who 206 develop and test ES models, potentially resulting in model outputs that are more locally relevant in 207 those areas (30). Thus we might expect that ES ensembles perform better in countries with higher GDP, 208 Human Development Index scores, or research capacity. After accounting for spatial autocorrelation 209 (see Methods) and applying the Hoghberg correction to account for multiple tests, we found no 210 evidence that ensembles are more accurate in countries with higher GDP (even when accounting for 211 within-country variability using Gini metrics of inequality), with higher Human Development Index, or 212 with higher research capability (expressed as the percentage of people who are researchers and 213 proportion of GDP invested in research; Table 1). The results are consistent when using alternative 214 statistical approaches (Tables S7-9). These findings suggest global consistency in ensemble accuracy, 215 in relation to the potential drivers of variation that we tested (Table 1). A potential caveat is that if the 216 validation data themselves are biased (for example, less accurate across developing countries) then 217 true patterns in ensemble model accuracy could exist undetected.

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Table 1: One tailed correlations as F-values with significance of the inverse of deviance per validation datapoint (where increasing accuracy is represented by increasing the inverse of deviance) of the five ecosystem service (ES) ensembles against globally available metrics that could potentially impact model accuracy. One-tailed tests were applied to test the hypothesis that the ensemble accuracy increases with higher values of each development/equality measure (two-tailed is presented in Table S7, including effect sizes). Degrees of freedom were standardised at 178 following a bootstrap convergence model for all services. Significance of the presented F-values were assessed taking account of multiple tests, using Hochberg's step-up correction with 8 tests per ES. An interaction model is added testing for interactions between GDP per capita and income equality, reflecting that income may be better represented using both mean and variance. To conform to the normality assumptions of the analysis, all metrics were arcsine transformed, with the exception of GDP per capita, which was log₁₀-transformed, and the Human Development Index, which was not transformed. See Table 3 for the sources of each validation dataset.

	Water Supply	Recreation	AG Carbon	Fuelwood Production	Forage Production
Accuracy Improvement (inverse of deviance) Ensemble vs. a random selected model (median among models) ⁺	14%	6.1%	6.1%	3.4%	2.7%
Spatial Autocorrelation [‡]	15.3***	14.6***	211***	0.47	0.14
Development/Equality per country					
GDP per capita	1.38	<0.01	1.21	3.58	0.24
Human Development Index	1.51	<0.01	0.14	6.43	0.25
Income Equality (Gini index)	0.17	6.69	1.37	<0.01	0.71
% People in R & D	1.44	<0.01	0.15	4.85	0.08
% GDP to R & D	0.08	<0.01	0.14	3.79	0.37
Interaction model					
GDP per capita	1.76	0.18	0.16	1.29	0.02
Income Equality	1.67	0.22	0.16	0.50	0.02
GDP x Income Equality	0.06	0.34	1.04	0.16	2.67

⁺Mean of pairwise comparisons per 1000 bootstrap runs; ⁺Two sided tested without direction; *** P <0.001 corrected.

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Finally, whilst the five ES ensembles made available here contribute to addressing the capacity gap, practitioners will often require accurate ES information on many additional services, including many for which there are no models (14). ES theory on bundles suggest that values for different ES can be spatially related to each other, either positively or negatively (2). However, spatial correlations among ES, while they do occur, may vary geographically, meaning there is no consistent correlative relationship among ES over large spatial scales (*29*). To test this, we spatially correlated each global ES ensemble output with the output of all other ES ensembles, both as a group (or 'bundle'; i.e. for all ES ensembles combined) and for each ES individually. Our results showed ES 'bundles' to be a relatively poor predictor of an additional ES (Figure 3). Similarly, most ES ensembles were not well correlated with other ES on an individual ES basis.

231 Discussion

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232 To help fill a major capacity gap in terms of available ES information for many countries, we have provided globally consistent ensemble data on five ES (https://doi.org/10.5285/bd940dad-9bf4-40d9-233 234 <u>891b-161f3dfe8e86</u>), as well as the code required to produce them (<u>github.com/GlobalEnsembles</u>). 235 Finding increased performance through use of ensemble approaches is common in other fields (20), 236 although an increase is not universal (31). Due to underlying assumptions, model predictions (including 237 those from ES models) are all potentially biased in direction and amount, with biases varying among 238 models due to their specific construction and available input data (20). The improvement in accuracy 239 when using ensembles likely derives from suppression of idiosyncratic differences by inclusion of 240 multiple possible system representations (termed a 'portfolio effect'), providing a more reliable average estimate (20, 32). However, this effect is lessened if assumptions, and therefore concomitant 241 242 biases, are shared across models (20). This highlights the importance of including: i) multiple model 243 outputs in model ensembles (33), including from models not explicitly identified as ES models, such as 244 hydrological models (20); and, ii) where data are available, model validation (8) - see Dormann et al. 245 (32) and Hooftman et al. (20) for further theoretical explorations. Using ensembles also improves 246 consistency across independent studies. For example, considering two studies applying different 247 models in different locations, it is uncertain how comparable the findings are (4). However, if both 248 studies use model ensembles, even if the ensemble approaches are not identical, results will be more 249 comparable. This is because variation among ensemble approaches is substantially lower than among 250 individual models (20) - resulting in greater consistency and coherence. Thus, potential applications of 251 ES ensembles include supporting nations' efforts to implement natural capital accounting (3). 252

253 Our finding that global ES ensembles perform just as well in less wealthy regions with lower research 254 capacity, where this information is often most needed, emphasises the utility of these modelled data. 255 This might reflect that ES models are increasingly tested and parameterized using global-scale Earth 256 Observation data. In addition to the ensemble maps themselves, we provide estimates of accuracy 257 (https://doi.org/10.5285/bd940dad-9bf4-40d9-891b-161f3dfe8e86). The ability to quantify accuracy 258 when it comes to ES is often lacking and, at worst, this can result in perverse outcomes – with the 'pot 259 luck' associated with model selection (i.e. without a priori accuracy information) sometimes resulting 260 in implementation of low-accuracy outputs and suboptimal decisions (8, 19). For policy and decision 261 making, accuracy estimates are as important as the ES maps themselves, and the lack of information 262 about uncertainty is one driver of the 'implementation gap' between ES research and its incorporation 263 into policy and decision making (16). By providing accuracy maps we are directly addressing this 264 certainty gap. However, future work should seek to improve on these accuracy maps, particularly 265 through the collection and inclusion of additional validation data at local scales, as using the national-266 and watershed-scale validation data that is currently available may be a poor proxy of model accuracy 267 at local-scales.

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269 Important capacity gaps remain. Most ES research predominantly focusses on a limited set of material 270 and regulating services because the data are widely available, and their underlying processes are 271 relatively well understood (*34*). This means our current ability to assess or predict unmodelled ES is 272 low. We found that ensembles, whether as an individual ES or as a bundle, do not accurately predict 273 other ES at global scales. It could be that as more ES are included in a bundle, predictive power of the 274 bundle for unmodelled ES improves; in a recent analysis global maps resulting from individual models 275 for 12 ES show high correlations between any one service and the remaining 11 (*2*). This is possibly because the more and more diverse ES that are included, the more likely that unmodelled ES will also
be represented by the same set of ecosystems, either because they are similar to modelled ES or simply
by chance. In general, the utility of the bundle approach is debated, with Spake et al (29) suggesting
that a hypothesis-driven approach is required to predict relationships between ES. Ultimately, whilst
individual models are available for more ES than are presented here, model development is urgently
required before ensembles of additional ES can be assessed.

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283 Practitioners show both capacity and willingness to engage with accuracy information when it is made 284 available (14). Accuracy estimates allow practitioners to determine what level of confidence is 285 acceptable to them and to use their own expertise to make potentially contentious decisions (35). 286 Given limited resources, accuracy information can play an important role in prioritisation. For example, 287 the accuracy of estimates may be vital in distinguishing between two sites with high levels of ES 288 production. Another example could be a decision to give a site with high accuracy of medium ES levels 289 lower priority over a potentially high-value site with medium or low accuracy; this is contentious, but 290 defensible if accuracy information is transparently conveyed to practitioners. Thus, providing 291 estimates of accuracy should become standard practice within the ES community (22). High levels of 292 inaccuracy or uncertainty of ES estimates should not lead to inaction, but instead highlights the risks 293 of making decisions using poor data, what data may need to be gathered to improve model inputs, or 294 the need to develop new or improve existing ES models. The model-estimated quantity of ES and its 295 accuracy should not be the only metrics considered in decision-making. For example, as the wellbeing 296 of some marginalised groups may depend on ES where models or data are lacking, or uncertainty is 297 high, therefore it is critical to incorporate local knowledge and values in any decision making process 298 (2). Indeed, model accuracy is one of a range of metrics considered by practitioners when determining 299 whether model outputs can be used to support decision-making, with others including spatial 300 resolution and the ability to incorporate scenarios (14). Thus, simply reducing uncertainty is not 301 necessarily going to lead to better policy decisions. However, in regions with a large capacity gap, 302 practitioners lack any comprehensive spatial data on most ecosystem services. For these regions, our 303 1 km² resolution ES ensemble outputs provide, at a minimum, some data with a level of validation and 304 associated accuracy at little to no cost to the practitioner (14).

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We conclude that ensemble modelling of ES can help reduce capacity and certainty gaps by, for example, making more accurate ES estimates freely available. We suggest ES scientists adopt ensemble approaches (shown here to be, on average, a more accurate approach than using individual models), and accompany model outputs with estimates of uncertainty. These changes may help reduce the implementation gap between ES research and policy and decision making (*14*, *34*), in particular for assessments by IPBES and the Intergovernmental Panel on Climate Change.

313 Materials and Methods

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315 We developed and tested (against validation data) ensembles of models for five ecosystem services 316 (ES; Figures 1 & 4) for which there are both a variety of models which are feasible to run at a global-317 scale (8, 20) and accessible independent validation data. We used model output estimates of ES (listed 318 in Table 2) to create ensembles, and then validated them against independent data (Table 3) using 319 methods developed previously for the UK (20) and sub-Saharan Africa (8). To ensure comparability 320 among model outputs, we standardised them by normalising outputs from individual models prior to 321 creating ensembles, following the same procedure for the validation data. We explored the spatial variation in accuracy of ES ensembles, using a variety of metrics. Finally, we investigated the use of ES 322 323 ensemble 'bundles' as proxies for other ES. We depict our overall process in Figure 4 in 6-steps. Our 324 calculations were performed using Matlab v7.14.0.739, ArcMap 10.7 and ArcPro 2.7, employing Arcpy 325 coding for loops. Relevant code can be found at github.com/GlobalEnsembles. 326



Figure 4: Schematic representation of our analysis, with arrows showing information flows. Numbers represent the steps within our methods; input tables and result figures are indicated.

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331 <u>1. Run and collate models</u>

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333 We collated models for this study according to their availability and feasibility to be run at a global 334 scale, and to reflect different approaches to modelling ES, obtaining appropriate registrations and 335 licenses if necessary. The collated models are summarised in Table 2, including their output grid sizes 336 (spatial resolution) – as well as whether the model outputs are existing (*i.e.* can be found online; e.g. 337 10, 31), are generated online (ARIES, Co\$ting Nature, WaterWorld), or can be calculated with a desktop tool (InVEST) or in local ArcGIS environment (Scholes, TEEB). For models that require input data choices 338 339 (InVEST, Scholes, TEEB), we refer to SI-1 for details and supporting data. For models that were taken 340 from Willcock et al. (8) and Hooftman et al. (20), we refer to the descriptions in those papers.

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Table 2: Summary information for the individual ecosystem service models used in this study.

Model	Ecosystem Service	Details	Model Output Resolution	
Multi service frameworks				
ARIES k.explorer (23) for year = 2020 integratedmodelling.org/modeler	 Recreation[†] AG carbon Forage production[‡] Fuelwood production¹ 	Recreation run online per country; carbon follows (36); all in tonnes per hectare, except recreation in normalised # of people (SI-1-4)	0.008333° Mostly worldwide	
Co\$ting Nature (25) policysupport.org/costingnature	 Water Supply AG carbon Recreation^{†§} Forage production Fuelwood production 	Run online as 10° tiles; subsequent among tile normalisation; all unitless normalised indexes, except water in m ³ per year.	0.008333° Not above 60° North	
InVEST v3.8.7 (24) naturalcapitalproject.stanford.edu/- software/invest	 Water Supply AG carbon Recreation[§] Forage production[‡] Fuelwood production ¹ 	Desktop tool, parameterised for this project (SI-1-1). Water supply in m ³ per gridcell; recreation in number of photo uploads; carbon/forage/fuelwood in tonnes per hectare.	0.008333° Worldwide	
Lund-Potsdam-Jena General Ecosystem Simulator (LPJ-GUESS) (37)	- Water Supply	Data set from (8) and run as described therein. Water supply in	0.5° Worldwide	

	 AG carbon Forage production[®] Fuelwood production[¶] 	m ³ per gridcell; carbon/forage/ fuelwood in tonnes per gridcell.	
TEEB via Costanza <i>et al.</i> (<i>38</i>)	 Water Supply AG carbon Recreation Forage production[‡] Fuelwood production 	In local GIS environment (SI-1-2) , all in <i>U</i> S-\$ for the year 2007 as provided by (<i>38</i>)	0.002778° Worldwide
Scholes(<i>39</i>) via Willcock <i>et al.</i> (<i>8</i>), livestock distributions extended worldwide	 Water In local GIS environment extended Supply from (8); SI-1-3. Water supply in positive growth days; forage in livestock units per hectare. 		0.008333° Worldwide
Single service models			
Aqueduct Global Maps 2.1 (WRI) (40): accumulated water run-off wri.org/data/agueduct-global-maps-21-data	- Water Supply	Existing data; as available blue water (m ³) per catchment outlet	Watershed Polygons Worldwide
European map of above ground biomass stocks	- AG carbon	Existing data, from (20); as tonnes	0.008333° Europe only
ESA CCI Biomass Climate Change Initiative (42) data.ceda.ac.uk/neodc/esacci/- biomass/data/agb/maps/v2.0/geotiff/2018	- AG carbon	Existing data; as tonnes per hectare	0.0008888° Worldwide Forest only
FAO combined gridded livestock distributions fao.org/livestock-systems/globaldistributions	 Forage production 	Existing data, summed LSUs among types (SI-2) per gridcell	0.08333° Worldwide
Integrated GEOCARBON global forest biomass (28) lucid.wur.nl/datasets/high-carbon-ecosystems	- AG carbon	Existing data; as tonnes per hectare	0.01° Worldwide. Forest only
Gilbert <i>et al.</i> (<i>43</i>); Combined gridded livestock distributions dataverse.harvard.edu/dataverse/glw 3	 Forage production 	Existing data, summed LSUs among types (SI-2) per gridcell	0.08333° Worldwide
Global Forest Watch, above ground biomass (44) data.globalforestwatch.org/-datasets/above- ground-live-woody-biomass-density/data	- AG carbon	Existing data; as tonnes per hectare	0.00025° Worldwide Forest only
JRC Above ground Biomass (45) data_jrc.ec.europa.eu/dataset/biomass	AG carbon	Existing data; as tonnes per hectare	0.0008333° Europe only
Chaplin-Kramer <i>et al.</i> (2)	- Recreation	Existing data in number of people per gridcell	0.01667° Not above 60° North
WaterWorld (46): Accumulated water run-off policysupport.org/waterworld	- Water Supply	Run online per available catchment in m ³ per catchment outlet	0.008333° Partially Worldwide
WaterWorld (46): Water Budget per cell policysupport.org/waterworld	- Water Supply	Run online per available catchment in m ³ per gridcell	0.008333° Partially Worldwide
Single service Carbon models with masked use	for Grazing and F	uelwood	-
Avitabile <i>et al. (28</i>): carbon in vegetation lucid.wur.nl/datasets/high-carbon-ecosystems	 AG carbon Forage production[‡] Fuelwood production[¶] 	Existing data; as tonnes per hectare	0.008333° Tropics only
Conservation International Total Carbon in vegetation (47) <u>conservation.org/projects/-</u> irrecoverable-carbon	 AG carbon Forage production[‡] Fuelwood production[¶] 	Existing data; as tonnes per hectare	0.002695° Worldwide
Kindermann <i>et al. (48</i>) above ground biomass stocks	 AG carbon Forage production[‡] Fuelwood production¹ 	Existing data, from (<i>20</i>) ; as tonnes per hectare	0.008333° Worldwide
ORNL DAAC (NASA), above ground biomass density (<i>49</i>) <u>daac.ornl.gov/cgi-bin/</u>	 AG carbon Forage production[‡] Fuelwood production¹ 	Existing data; as tonnes per hectare	0.002778° Worldwide

¹ tincluding post-processing with a further data set (SI-1-4); based on above ground (AG) carbon with an ‡grassland and ¹woodland MODIS
 ¹ land cover mask following⁹ (SI-3); [§]realised service based on photo uploads; © combined C₃ and C₄ carbon.

346 All model outputs were projected to WGS 1984 (EPSG 4326) and rescaled to a 0.008333° grid 347 (approximately 1km at the equator), resampling models where necessary (Table 2). Generally, when 348 upscaling, cells were aggregated by calculating the mean of the grid cell values with no-data cells 349 ignored; when downscaling ArcPro's bilinear recalculation algorithm was used for resampling. This 350 latter resampling resulted in a smooth transition by assuming values of smaller cells via linear 351 extrapolations from neighbouring cells (e.g. for LPJ, gridded livestock). Small-scale non-linearity (e.g. 352 as a result of unmodelled features) is not included in this downscaling, as such an output would heavily 353 depend on post-processing assumptions and inputs and be a model in its own right. Rescaling factors 354 are not needed during these calculations since these will not change relative values (*i.e.* resulting from 355 subsequent normalisation; Step 3). All outputs were clipped and aligned to the exact same extent with 356 standard number of rows and columns (43,200 x 18,600), using ArcPro's bilinear recalculation 357 algorithm.

358

359 Whilst all model outputs were obtained at global scale, not all cover the entire globe (Table 2). Only 360 the terrestrial globe was considered, but there were other specific constraints. For example, servers 361 for certain online models restricted overly large data flows. Specifically, ARIES k.explorer was not able 362 to run the recreation module per country for North America and parts of Europe because of the high level of detail in the supporting maps (23); WaterWorld was not able to run the largest watersheds 363 364 such as the Amazon basin, the Mississippi and the Yangtze (46). Furthermore, Co\$ting Nature is limited 365 to latitudes below 60° north due to lack of input data for northern regions (25). We used above ground (AG) carbon models that were region specific; two for Europe (41, 45), one for the tropics (28) and 366 367 three that were forest vegetation specific (28, 42, 44).

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370

369 2. Validation data sets

371 Our validation data sets are listed in Table 3 (and mapped in SI-4). Broadly, they include either informed 372 expert statistics (such as country-level statistics from the FAO [forage production and fuelwood] and 373 recreation values from the World Travel and Tourism Council), or actual biophysical measurement 374 (tree inventory plots for AG carbon, and weir data for water flow):

- 375 • Our water supply validation data set is catchment-based. Specifically, we used a Global Runoff 376 Data Centre (GRDC) data set with 3746 weirs (Table 3; Figure S1), covering all regions but not 377 all land area. For each weir, bespoke catchments polygons were delineated using the a 90m 378 SRTM Digital Elevation Map (50), following Willcock et al. (8).
- 379 The recreation validation data consisted of the 178 available country sheets for economic and • 380 employment impact of travel & tourism of the World Travel and Tourism Council for 2019 (i.e. pre-Covid), providing the estimated total GDP of Tourism and Travel in US\$. It also contains 381 382 estimates for the proportion spent on business and leisure, and the proportion that is from 383 domestic and international tourism. Three of the five recreation models represent leisure-384 oriented local access to nature, including gravity models (51). Therefore, to use validation data 385 comparable to our modelled outputs, we multiplied the Tourism and Travel GDP with the 386 proportions for leisure and domestic to get to 'GDP of domestic recreation for leisure'.
- The AG carbon validation data is a combination of pan-tropical biomass in forest plots from 387 • 388 ForestPlots.Net (28), and from the United Kingdom assessment of carbon in all forest estates 389 (20). By using both data sets, we are able to validate the models in both temperate and tropical 390 contexts. See Avitabile et al. (28) and Hooftman et al. (20) for further details.
 - The fuelwood and forage production validation data are country-level statistics from FAO for 2019 (195 countries available) and 2018 (208 countries) respectively (Figure S2).

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394 Each data set has associated uncertainties (8) but after an extensive review of data, we identified these as the best-suited reference values for validation (i.e. metrics that corresponded most closely to those

395 396 modelled, have been published in the peer-reviewed literature and/or widely accepted as an 397 authoritative source [e.g. FAO statistics], and are available globally or for a large number of countries). 398 Both model and validation data are normalised (see below) to ensure comparability and remove 399 unavoidable differences in exact units. The validation data are as independent as feasibly possible from 400 the models; however, due to data deficiency, some aspects of an individual model may have been 401 trained with local census data which could, in part, relate to validation data. For example, gridded 402 livestock from FAO and Gilbert et al. (43) are trained on various regional census data, some of which 403 may have been included in the national-scale forage production validation data, and some of the plots 404 from Avitabile et al. (28) may have been used to estimate the carbon stocks per land cover class per 405 ecofloristic zone as used in ARIES (23).

406

Table 3: The empirical validation data sets used in this study (mapped in SI-4). ES models need to be evaluated against the real world to determine if they are able to provide sufficiently accurate information for regional- or local-scale policy- and decision-making. Since the 'true value' can never be absolutely determined, acceptable reference values must be used. Empirical data can be used as reference values to evaluate ES model accuracy (8). Although such reference values are likely to have errors associated with them and may not be totally representative of the true values (8), this approach is widely accepted in environmental sciences (52).

Service	Validation Set	Description	Original Resolution	Details
Water Supply	Global Runoff Data Centre: river discharges	3746 selected stations. Mean annual water flow per hectare catchment (m ² ha ⁻¹)	Catchments as polygons (SI-4)	Selected on still running after 2000 and containing at least 25 years of data. <u>bafg.de/GRDC/EN/Home</u>
Recreation WTCC: Tourism Economic Impac Reports per cou		Total GDP of domestic recreation for leisure in US\$ for 178 countries	Country (GAUL-2) polygons.	Country sheets for 2019, calculated as recreation GDP contribution (US\$) x [% domestic spending x % leisure spending]. wttc.org/Research/Economic- Impact.
AG carbon	 Pan-tropical biomass in forest plots 	ABG stock in tonnes per hectare for 14,478 forest plots ³⁵	Point data	Tropical region. Pan-tropical biomass reference data <u>lucid.wur.nl/datasets/high-carbon-</u> <u>ecosystems</u> .
	2. United Kingdom carbon in forest estates	Mean ABG stocks in tonnes per hectare from 1606 estates.	Forest polygons	Temperate region. Modified data taken from (20), original data from UK Forest Research
Fuelwood production	FAOStat: Wood fuel per country	Wood fuel in m ³ , summed non-coniferous & coniferous for 2019 for 195 countries	Country (GAUL-2) polygons.	fao.org/faostat/en/#data/FO
Forage production	FAOStat: Livestock per country	Summed livestock units per country for 2018 for 208 countries	Country (GAUL-2) polygons.	Animals are: Asses, Buffaloes, Camels, Cattle, Chickens, Goats, Horses, Mules, Pigs & Sheep. <u>fao.org/faostat/en/#data/EK</u>

407

408 <u>3. Model postprocessing and normalisation</u>

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410 General model output postprocessing included projecting to WGS 1984, rescaling and clipping to the 411 specified extent (step 1), as well as detecting and masking no-data values. The latter was especially 412 applicable for forest only biomass/carbon data sets (Table 2), as well for sea/large water bodies in 413 various model outputs. In making ensembles, true zeros contribute to the average, whereas no-data 414 are ignored. Postprocessing of ARIES and Co\$ting Nature model outputs with additional data (marked 415 + in Table 2) is discussed in SI-1-4. This includes the procedure of among tile rescaling of Co\$ting 416 Nature, as the framework produces outputs in 10°-tiles which are individually normalised. Therefore, 417 tiles need to be rescaled using other global-scale estimates (SI-1-4). AG carbon model output 418 postprocessing with MODIS land cover (53) masks into forage production and fuelwood outputs 419 following (8) as detailed in SI-3.

420

To ensure comparability among model outputs, we standardised by normalising each individual model output prior to making ensembles. This normalisation followed (*13, 20*) and allowed us to address differences in units among models, such as monetary benefit transfer vs. satellite-based tree cover 424 densities or water run-off, and negates the need for conversion factors (e.g. between biomass and AG carbon). To avoid impacts of extreme values without eliminating these data-points, we employed a 425 426 double-sided Winsorising protocol for normalisation (20), using the values associated with the 2.5% 427 and 97.5% percentiles to define the minimum (0) and maximum (1) values (values below or above 428 these percentiles became 0 or 1 respectively). Winsorising loses the extremes and so does curtail skew, 429 but avoids influences of very large and very small values (20). The Winsorising procedure can be found 430 can be found at our GitHub account (github.com/GlobalEnsembles/Winsorising), both as Matlab and 431 arcpy coding. The validation data sets were subjected to the same Winsorising protocol. It must be 432 noted that, even when modelling the same ES, many of the ES models estimate different constructs to 433 some extent, often with varying units (Table 2). However, since our statistical analyses focused on 434 relative ranking, it is unlikely that these uncertainties impacted our findings greatly [see (8) for a full 435 discussion].

436

438

437 <u>4. Generating spatial ecosystem service ensembles.</u>

The procedures to generate different types of ES model ensembles are discussed in Hooftman *et al.* (*20*). Here we focus on an unweighted ensemble, which is the median value of the model outputs calculated per grid cell. A selection of weighted methods developed by (*20*) (including mean, PCA, correlation coefficient, regression to the median, leave-one-out cross validation, and log-likelihood approaches) are reported in SI-7. These alternative ensemble approaches show consistent patterns and comparable accuracy to the relatively simple median ensemble.

445

446 For recreation, AG carbon, fuelwood and forage production our ensembles were based on per-grid cell 447 estimates of the respective model outputs. Here, models for AG carbon, fuelwood and forage 448 production are comparable point-based estimates of local resources, although differing in complexity 449 and initial assumptions (8, 20). Additionally, our recreation ensemble comprises different modelling 450 methods which provide comparable predictions of potential recreational pressure: observations 451 [Photo uploads: (24) and (25)], population movement through gravity functions [(2) and (23)], and 452 benefit transfer (38); see SI-1-4 for a full discussion. For water supply, our ensembles are accumulated 453 flow estimates following the global HydroSHEDS catchments definition (54). For grid cells, ensembles 454 were created using ArcPro Cell Statistics module - with the median or standard deviation as the input 455 statistic. Due to the way certain models accumulated water flows (WaterWorld, Aquastat) a per-grid 456 cell approach was not possible for water supply, so the sum of grid values within catchment polygons 457 was calculated for each catchment. In the case of accumulated flow models (WaterWorld, Aquastat), 458 we used the maximum value per polygon assumed to be the flow out of the HydroSHED pour point. 459 Since HydroSHEDS information do not contain the spatial location of the exact pour point we could not 460 correct for differences in routing information as we do for the GRDC validation catchments (Step 5). 461 We employed a forced 0.001° grid size to minimise edge effects.

462

As all models are normalised to the same 0-1 scale, calculations do not require any additional scaling factors. The spatial representation of the ensembles and variation are generated on the same extent and grid as described under Step 1, and can be downloaded from the Environmental Informatics Data Centre (<u>https://doi.org/10.5285/bd940dad-9bf4-40d9-891b-161f3dfe8e86</u>). The water ensembles are there available as HydroSHED (*54*) defined accumulated water flow (vector format), the other four ES as geotiffs (raster format). Since not all model outputs are globally comprehensive, variation is expressed by a standard error of means as $(\frac{\sigma_{(x)}}{\sqrt{n_{(x)}}})$, instead of standard deviation (σ), with *n* the number

470 of models per grid cell *x*. The ensembles are renormalised to represent the full 0-1 range.

471

472 <u>5. Validation of accuracy</u>

473

474 After creating the ensembles, the model and ensemble outputs were calculated at the spatial 475 resolution of the validation data. For recreation, fuelwood and forage production, the validation data 476 are available on a per-country basis, so this was done by calculating the sum of all model ensemble 477 grid cells within countries. Country definitions followed FAO Global Administrative Unit Layers (GAUL) 478 level 2 with 2014 definition. This map includes separate polygons for overseas territories. When 479 overseas territories were treated separately in one of the validation data sets (e.g. Martinique [FR] or 480 British Virgin Island [UK]) those values were extracted as separate data-points from the ensembles. 481 We refer to all these spatial units as 'countries', although not all units have that designation. For each 482 individual model, outputs were obtained for each country polygon with the ArcGIS Zonal tool with a 483 forced 0.001° grid size to minimise edge effects – *i.e.* all predicted values were obtained by down-484 sampling into 0.001° grid cells. For AG carbon plots, the point-based location of the forest plot was 485 used as the mean value of underlying 0.001° gridcells. For grid-based water supply estimates the sum 486 of grid values per watershed polygon was employed. In the case of accumulated flow models 487 (WaterWorld, Aquastat), we corrected for potential small scale differences in flow routing among 488 these models by taking the maximum flow value within a 0.041665° range (5 cell widths) of the GRDC 489 reported location of the weir station (20), without exceeding the aligned watersheds. We note that, 490 these validation data are diverse (Table 3), being collected using a range of methods of varying 491 reliability, including: expert opinion (e.g. country-level statistics from the FAO) and biophysical 492 measurement (e.g. tree inventory plots, and weir data on water flow). As such, each dataset has 493 associated uncertainties (55) but, since the 'true value' can never be absolutely determined, provides 494 useful reference values for validation (8, 13, 52). However, given that the datasets covered a wide 495 range of methods and our focus was on ranked correlative relationships (below), there is unlikely to 496 be systematic bias and so data quality issues should have a low impact on our results. We refer to 497 references (8) and (13) for a full discussion of ES model validation.

498

499 To create ES ensemble proxy services, we followed the procedure as above -e.q. AG carbon summed 500 per country to compare to national-scale validation data; recreation, forage production and fuelwood 501 summed within catchments (for comparison to global runoff data) and at the point location of the 502 forest plots (for comparison to AG carbon data). To be able to use accumulated water flow as proxy 503 for country-validated services we split the HydroSHEDS by countries, generating sub-catchments 504 where they crossed borders. Following this, data extraction and ensemble procedure was followed 505 anew as described above. Similarly, for forest plot locations water flow ensembles were generated for 506 the plot locations only.

507

508 Ensemble, bundle and model output accuracy was assessed following the inverse of the deviance (D^{\downarrow}) 509 as was developed in (8) following:

510 511

512

 $D^{\downarrow} = 1 - \left(\frac{1}{n} \times \sum_{x}^{n} |X_{(x)} - Y_{(x)}|\right)$

Eqn. 1

in which n = the number of spatial data points, x a spatial data point, X(x) the normalised validation value for x, and Y(x) the normalised value for the model or ensemble tested.

513 We also conducted rank-order comparisons using Spearman's ρ as an accuracy measure, which 514 showed consistent results (SI-5).

515

516 To allow statistical comparisons we bootstrapped with 1000 runs for 10% of the data sets (AG carbon, 517 water supply) or 100 data-points (country validations) reporting the mean and standard deviation 518 across these bootstraps. We tested all accuracies within the same bootstrap run, allowing pairwise 519 comparisons. We assessed accuracy differences with pairwise t-tests (Matlab ttest-tool). The mean of 520 pairwise differences per run is generally larger than the difference between the averaged accuracies 521 as shown in Figure 3. The pairwise combinations included median accuracy among models [i.e. 522 indicating a random pick among models (20)], the median ensemble and the median ensembles of the 523 other four service as proxies. Since we used the same statistical test five times per service per 524 comparison, we employed a Hochberg's step-up correction (56) to account for multiple tests on the 525 resulting average p-values. Hochberg's step-up correction is seen as more powerful than Sidak, 526 Bonferroni and Holms correction methods, which are known to underestimate true effects (56). A 527 comparison with six other approaches to creating ensembles from (20) are reported in SI-7.

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6. Spatial comparison of ensemble accuracy with development and equality per country

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531 We explored possible drivers of the spatial variation of ES ensemble accuracy, testing if ensembles are 532 more accurate in more economically developed countries with relatively higher levels of data, research 533 and model development. We used the following metrics:

- 534 The Human Development Index (HDI) of 2019, as metric developed by the United Nations 535 Development Programme being a summary measure of proxies for three important ends of 536 education, and goods (57). Downloaded development: access to health, from 537 hdr.undp.org/en/indicators/137506.
- 538 • The following World Development indicators were downloaded from The World Bank 539 (databank.worldbank.org/home.aspx) using 2018 data (except GDP per capita) or the latest 540 available entry before:
- 541 GDP per capita downloaded from World Bank 2019 in US\$ Purchasing Power Parity, 0 542 supplemented for missing countries by CIA data for 2018 (cia.gov/the-world-543 factbook/field/real-gdp-per-capita/country-comparison).
- 544 Income Equality following the Gini index measuring the extent to which the 0 545 distribution of income among households within an country deviates from an equal 546 distribution.
 - The number of researchers engaged in research and development (R&D), expressed 0 as per million.
 - Gross domestic expenditures on research and development (R&D), expressed as a 0 percent of GDP.
- 552 After exporting all above outputs to Matlab v7.14.0.739 we correlated these metrics one by one 553 (Metric) with the per-validation point accuracy of the median ensemble, calculated as the inverse of deviance per point $(D_{(x)}^{\downarrow} = (1 - |X_{(x)} - Y_{(x)}|))$, using a SS-type I model with the Matlab Anovan tool: 554

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- $D_{(x)}^{\downarrow} \sim \beta_0 + \beta_1 Auto_{(x)} + \beta_2 Metric_{(x)} + \varepsilon$ Eqn. 2
- 556 557

in which $D^{\downarrow}_{(x)}$ is the accuracy for polygon x, with effect sizes β and error ϵ .

558 We incorporated a correction for potential spatial autocorrelation through inclusion of a covariate 559 (Auto) prior to estimating the correlation of the metric of interest, describing relatedness between individual outputs in deviance with the Euclidean distances among centroids of polygons/points (13, 560 561 58). We used a maximum spatial autocorrelation effect range of 5°. To equalise degrees of freedom 562 across services and avoid high degrees of freedom (df) inflation of F-values for AG carbon and water 563 supply - resulting in near-zero p-values even for very weak effects - an iteration method was used 564 taking a standard sample size of 178 datapoints (the minimum N across services). Not setting a default 565 number of bootstraps, we used a convergence iterations method, stopping the iterations after the 566 mean Sum of Squares of each factor over all iterations will not have changed by more than 0.05% with 567 an extra iteration, consistently for 25 tries sequentially (see codes on github.com/GlobalEnsembles). 568 Furthermore, we explicitly test for potential higher accuracy in more economically developed countries 569 using a one-sided p-value distribution (two-sided is reported in SI-5). The presented F-values 570 themselves are mirrored accordingly to represent the one-sided significance distribution. Since, for each ES, all metrics and the interaction (Eqn. 3) are calculated for the identical set of $D^{\downarrow}_{(x)}$ per point 571 572 and hence the spatial autocorrelation among those, we employed a Hochberg's step-up correction (56) 573 of significance to account for the use of 8 tests, as in step 5. Identical tests using Spearman's ρ as 574 accuracy measure are reported in SI-5.

576 Since individual wealth may be better represented by the distribution of wealth around the mean (*i.e.* 577 GDP per capita), we also ran Eqn. 2 as a two factor interaction model for GDP per capita and income 578 equality with type I Sum of Squares between spatial autocorrelation and the tested factors and type III 579 among factors and *interaction* following:

580

581

 $D_{(x)} \sim \beta_0 + \beta_1 Auto_{(x)} + \{\beta_2 Equity_{(x)} + \beta_2 Equality_{(x)} + Interaction + \varepsilon\}$ Eqn. 3

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